

Integrability and Matrix Ansatz

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The logo for LAPTh (Laboratoire d'Annecy-le-Vieux de Physique Théorique) features the letters 'L', 'A', 'P', 'T', and 'h' in a stylized, blue, serif font. The 'A' has a red dot above it, and the 'h' has a red stroke above it.

General context

- Thermodynamical equilibrium stationary state: no particle or energy flow.

$$P_{eq}(\mathcal{C}) \sim e^{-\frac{E(\mathcal{C})}{k_B T}}$$

- Non-equilibrium stationary state: particle or energy currents

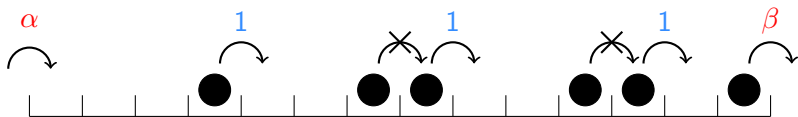
$$P_{eq}(\mathcal{C}) \sim ?$$

The matrix ansatz allows exact computations to get $P_{eq}(\mathcal{C})$.

We want to understand the matrix ansatz in the integrable system framework and generalize it to other models.

- 1 TASEP and Matrix Ansatz
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The TASEP model



Stochastic process on a one dimensional lattice with boundaries

- In the bulk, particles can jump to the right at the rate 1
- On the left boundary, particles enter at the rate α
- On the right boundary, particles leave at the rate β
- Fermi-like exclusion principle

This is an out-of-equilibrium system (there is a particle current)
The model is integrable

- Denote by $\mathcal{C} = (\tau_1, \tau_2, \dots, \tau_L)$ a configuration of the system.

$$\begin{array}{cccccccccccc} | & | & | & | & | & | & | & | & | & | & | & | \\ | & \bullet & | & | & \bullet & \bullet & | & | & \bullet & | & | & \bullet \\ \hline \end{array} \longrightarrow (0, 1, 0, 0, 1, 1, 0, 0, 1, 0, 0, 1)$$

- Denote by $P_t(\mathcal{C})$ the probability to be in configuration \mathcal{C} at time t .

Master equation

$$\frac{dP_t(\mathcal{C})}{dt} = \sum_{\mathcal{C}' \neq \mathcal{C}} M(\mathcal{C}, \mathcal{C}') P_t(\mathcal{C}') - \sum_{\mathcal{C}' \neq \mathcal{C}} M(\mathcal{C}', \mathcal{C}) P_t(\mathcal{C})$$

- At each site, we have 2 possibilities (0 or 1) $\rightarrow \mathbb{C}^2$ "local" space
- There are L sites $\rightarrow (\mathbb{C}^2)^{\otimes L}$ total configuration space

We gather the probabilities in a vector

$$|P_t\rangle = \begin{pmatrix} P_t((0, \dots, 0, 0, 0)) \\ P_t((0, \dots, 0, 0, 1)) \\ P_t((0, \dots, 0, 1, 0)) \\ \vdots \\ P_t((1, \dots, 1, 1, 1)) \end{pmatrix} \in (\mathbb{C}^2)^{\otimes L}$$

$$\text{Master equation : } \frac{d|P_t\rangle}{dt} = M |P_t\rangle \in (\mathbb{C}^2)^{\otimes L}$$

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The Markov matrix M can be written in terms of local jump operators

$$M = B_1 + \sum_{\ell=1}^{L-1} w_{\ell,\ell+1} + \bar{B}_L \in (\text{End}(\mathbb{C}^2))^{\otimes L}$$

$$B = \begin{pmatrix} -\alpha & 0 \\ \alpha & 0 \end{pmatrix}; \quad w = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}; \quad \bar{B} = \begin{pmatrix} 0 & \beta \\ 0 & -\beta \end{pmatrix}$$

$\text{End}(\mathbb{C}^2)$
 $\text{End}(\mathbb{C}^2 \otimes \mathbb{C}^2)$
 $\text{End}(\mathbb{C}^2)$

$$B_1 = \underbrace{B}_1 \otimes \underbrace{\mathbb{I}_2 \otimes \cdots \otimes \mathbb{I}_2}_{L-1}; \quad w_{\ell,\ell+1} = \underbrace{\mathbb{I}_2 \otimes \cdots \otimes \mathbb{I}_2}_{\ell-1} \otimes \underbrace{w}_{\ell,\ell+1} \otimes \underbrace{\mathbb{I}_2 \otimes \cdots \otimes \mathbb{I}_2}_{L-1-\ell}$$

$$\text{Master equation : } \frac{d|P_t\rangle}{dt} = M |P_t\rangle \in (\mathbb{C}^2)^{\otimes L}$$

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$\text{End}(\mathbb{C}^2)$
 $\text{End}(\mathbb{C}^2 \otimes \mathbb{C}^2)$
 $\text{End}(\mathbb{C}^2)$

The goal is to compute the stationary state: $M|S\rangle = 0$

Matrix ansatz (Derrida, Evans, Hakim, Pasquier):

$$\boxed{\bullet} \longrightarrow D \quad \mathcal{S}(\boxed{\bullet} \boxed{\bullet} \boxed{\bullet}) = \frac{\langle\langle W | E D E D D | V \rangle\rangle}{Z_5}$$

$$\boxed{} \longrightarrow E \quad Z_L = \langle\langle W | (D + E)^L | V \rangle\rangle$$

Algebraic relations (DEHP)

$$DE = D + E \quad ; \quad D|V\rangle\rangle = \frac{1}{\beta}|V\rangle\rangle \quad ; \quad \langle\langle W|E = \frac{1}{\alpha}\langle\langle W|$$

DEHP gives the right weights of the stationary state:

The vector we compute using this ansatz can be written in the compact form

$$|S\rangle = \frac{1}{Z_L} \langle\langle W | A_1 A_2 \cdots A_L | V \rangle\rangle \quad \text{with} \quad A = \begin{pmatrix} E \\ D \end{pmatrix}$$

- $\langle\langle W |$ and $| V \rangle\rangle$: additional space
They define a representation of the (E, D) algebra
- $1, 2, \dots, L$: \mathbb{C}^2 physical spaces \equiv Sites on the lattice
- **Tensor products** implied:

$$A_1 A_2 \cdots A_L = \underbrace{A \otimes A \otimes \cdots \otimes A}_L$$

$$A_1 = A \otimes \underbrace{\mathbb{I} \otimes \cdots \otimes \mathbb{I}}_{L-1} \quad \text{etc..}$$

The **bulk relation** $DE = D + E$ is equivalent to

$$w A \otimes A = \bar{A} \otimes A - A \otimes \bar{A} \quad \text{with} \quad A = \begin{pmatrix} E \\ D \end{pmatrix}, \quad \bar{A} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

So that

$$\begin{aligned} & (w_{12} + w_{23} + \cdots + w_{L-1,L}) A_1 A_2 \cdots A_L = \\ & (\bar{A}_1 A_2 - A_1 \bar{A}_2) A_3 \cdots A_L \\ & + A_1 (\bar{A}_2 A_3 - A_2 \bar{A}_3) A_4 \cdots A_L \\ & \quad \vdots \\ & + A_1 \cdots A_{L-2} (\bar{A}_{L-1} A_L - A_{L-1} \bar{A}_L) \end{aligned}$$

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So that

$$\begin{aligned} (w_{12} + w_{23} + \cdots + w_{L-1,L}) A_1 A_2 \cdots A_L &= \\ &= \bar{A}_1 A_2 \cdots A_L - A_1 \cdots A_{L-1} \bar{A}_L \end{aligned}$$

- The **left boundary condition** $\langle\langle W|E = \frac{1}{\alpha}\langle\langle W|$ is equivalent to

$$\langle\langle W|B A = -\langle\langle W|\bar{A}$$

$$\text{i.e. } \langle\langle W|B_1 A_1 A_2 \cdots A_L = -\langle\langle W|\bar{A}_1 A_2 \cdots A_L$$

- The **right boundary condition** $D|V\rangle\rangle = \frac{1}{\beta}|V\rangle\rangle$ is equivalent to

$$\bar{B} A|V\rangle\rangle = \bar{A}|V\rangle\rangle$$

$$\text{i.e. } \bar{B}_L A_1 A_2 \cdots A_L|V\rangle\rangle = -A_2 \cdots A_{L-1} \bar{A}_L|V\rangle\rangle$$

$$\text{with } A = \begin{pmatrix} E \\ D \end{pmatrix} \text{ and } \bar{A} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

These algebraic relations lead to a telescopic sum

$$M|S\rangle = \left(B_1 + \sum_{\ell=1}^{L-1} w_{\ell,\ell+1} + \bar{B}_L \right) |S\rangle = 0$$

$$\begin{aligned} |S\rangle &= \frac{1}{Z_L} \langle\langle W | A_1 A_2 \cdots A_L | V \rangle\rangle \\ &= \frac{1}{Z_L} \langle\langle W | A \otimes A \otimes \cdots \otimes A | V \rangle\rangle \\ Z_L &= \langle\langle W | (D + E)^L | V \rangle\rangle \end{aligned}$$

The Matrix ansatz allows to built the stationary state

Integrability of the TASEP

Bulk: R -matrix

$$R(x) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & x & 0 \\ 0 & 1 & 1-x & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \in \text{End}(\mathbb{C}^2 \otimes \mathbb{C}^2)$$

$x \in \mathbb{C}$ is the spectral parameter

$$P \frac{d}{dx} R(x) \Big|_{x=1} = w \quad \text{with} \quad P = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

The R -matrix:

- satisfies the **Yang-Baxter** equation

$$R_{12}\left(\frac{x_1}{x_2}\right) R_{13}\left(\frac{x_1}{x_3}\right) R_{23}\left(\frac{x_2}{x_3}\right) = R_{23}\left(\frac{x_2}{x_3}\right) R_{13}\left(\frac{x_1}{x_3}\right) R_{12}\left(\frac{x_1}{x_2}\right)$$

$$R_{12}(x) = R(x) \otimes \mathbb{I}_2, \quad R_{23}(x) = \mathbb{I}_2 \otimes R(x)$$

- is **unitary** $R_{12}(x)R_{21}(1/x) = 1$
- is **regular** $R(1) = P$
- $PR'(1) = w$
- obeys the **Markovian property** $\langle 1| \otimes \langle 1|R(x) = \langle 1| \otimes \langle 1|$, where $\langle 1| = (1, 1)$

Boundaries: K -matrices

$$K(x) = \begin{pmatrix} \frac{(-x\alpha + \alpha - 1)x}{x\alpha - x - \alpha} & 0 \\ \frac{\alpha(x^2 - 1)}{x\alpha - x - \alpha} & 1 \end{pmatrix}, \quad \bar{K}(x) = \begin{pmatrix} 1 & -\frac{(x^2 - 1)\beta}{-x^2\beta + x\beta - x} \\ 0 & \frac{x\beta - x - \beta}{-x^2\beta + x\beta - x} \end{pmatrix}$$

$$\left. \frac{d}{dx} K(x) \right|_{x=1} = 2B \quad \text{and} \quad \left. \frac{d}{dx} \bar{K}(x) \right|_{x=1} = -2\bar{B}$$

The K -matrices:

- satisfy the **reflection equation**

$$R_{12} \left(\frac{x_1}{x_2} \right) K_1(x_1) R_{21}(x_1 x_2) K_2(x_2) = K_2(x_2) R_{12}(x_1 x_2) K_1(x_1) R_{21} \left(\frac{x_1}{x_2} \right)$$

- are **unitarity** $K(x)K(1/x) = 1$
- are **regular** $K(1) = 1$
- $K'(1) = 2B$ and $\bar{K}'(1) = -2\bar{B}$
- obey the **Markovian property** $\langle 1|K(x) = \langle 1|$

Integrability: we define the usual double row **transfer matrix**

$$t(x) = \text{tr}_0 \left(\tilde{K}_0(x) R_{0L}(x) \cdots R_{01}(x) K_0(x) R_{10}(x) \cdots R_{L0}(x) \right),$$

where \tilde{K} is linked to \bar{K} in the following way

$$\bar{K}_1(x) = \text{tr}_0 \left(\tilde{K}_0\left(\frac{1}{x}\right) R_{01}\left(\frac{1}{x^2}\right) P_{01} \right)$$

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Properties

- $[t(x), t(x')] = 0$ (integrability of the model)
- It generates the Markov matrix

$$\frac{1}{2} \frac{dt(x)}{dx} \Big|_{x=1} = \frac{1}{2} K'_1(1) + \sum_{k=1}^{L-1} P_{k,k+1} R'_{k,k+1}(1) - \frac{1}{2} \bar{K}'_L(1) = M$$

- **Integrability** ensures that we can construct exactly the eigenvectors of the transfer matrix (and thus of the Markov matrix) using for instance the Bethe ansatz
- **Bethe vectors**: $t(x) \mathbb{B}(\bar{u}) = \lambda(x, \bar{u}) \mathbb{B}(\bar{u})$ when the set of parameters \bar{u} obeys the so-called **Bethe equations**
- However the **stationary state** is not easily obtained in this way since one should solve the Bethe equations to identify it

⇒ We want to recover the Matrix ansatz from R and K matrices

We want to generate the DEHP relations from R and K matrices

Let's define the vector

$$A(x) = \begin{pmatrix} E - 1 + x \\ D - 1 + \frac{1}{x} \end{pmatrix} \Rightarrow A(1) = \begin{pmatrix} E \\ D \end{pmatrix}, A'(1) = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

We want to generate the DEHP relations from R and K matrices

Let's define the vector

$$A(x) = \begin{pmatrix} E - 1 + x \\ D - 1 + \frac{1}{x} \end{pmatrix} \Rightarrow A(1) = \begin{pmatrix} E \\ D \end{pmatrix}, A'(1) = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\text{ZF relation : } R_{12} \left(\frac{x_1}{x_2} \right) A_1(x_1) A_2(x_2) = A_2(x_2) A_1(x_1)$$

$$\Leftrightarrow DE = D + E$$

GZ relation (Left boundary):

$$\langle\langle W|A(x) = \langle\langle W|K(x)A\left(\frac{1}{x}\right)$$

$$\Leftrightarrow \langle\langle W|E = \frac{1}{\alpha}\langle\langle W|$$

GZ relation (Right boundary):

$$A(x)|V\rangle\rangle = \bar{K}(x)A\left(\frac{1}{x}\right)|V\rangle\rangle$$

$$\Leftrightarrow D|V\rangle\rangle = \frac{1}{\beta}|V\rangle\rangle$$

Integrable approach to Matrix Ansatz:

We start with a unitary **R-matrix** $R_{12}(x)$ of size $r^2 \times r^2$, which obeys **YBE**, and the corresponding unitary **boundary matrices** $K(x)$ and $\bar{K}(x)$, of size $r \times r$, obeying the **reflection equation**.

Let $A(x) = \begin{pmatrix} X_1(x) \\ X_2(x) \\ \vdots \\ X_r(x) \end{pmatrix}$ where the elements $X_1(x), \dots, X_r(x)$ belong to some algebra.

The algebraic relations for the elements $X_1(x), \dots, X_r(x)$ are provided by the following relations

Bulk exchange relations:

ZF algebra

$$R_{12} \left(\begin{array}{c} x_1 \\ x_2 \end{array} \right) A_1(x_1)A_2(x_2) = A_2(x_2)A_1(x_1)$$

- Associativity of this algebra ensured by the Yang-Baxter relation.
- Another consistency relation ensured by the unitarity of the R-matrix.

$$PR'_{12}(1) A_1(1) A_2(1) = A_1(1) A'_2(1) - A'_1(1) A_2(1)$$

N.B.: $\bar{A} = A'(1)$ is not necessarily scalar!

Conditions on the boundaries:

GZ relation

$$\langle\langle W|A(x) = \langle\langle W|K(x)A\left(\frac{1}{x}\right), \quad A(x)|V\rangle\rangle = \bar{K}(x)A\left(\frac{1}{x}\right)|V\rangle\rangle$$

- A consistency relation is ensured by the reflection equation.
- Another consistency relation is ensured by the unitarity of the K matrices.

$$\langle\langle W|K'(1)A(1) = \langle\langle W|2A'(1), \quad \bar{K}'(1)A(1)|V\rangle\rangle = 2A'(1)|V\rangle\rangle$$

Define the Markov matrix $M = B_1 + \sum_{\ell=1}^{L-1} w_{\ell,\ell+1} + \bar{B}_L$ with local jump operators:

- $PR'(1) = w.$
- $K'(1) = 2B$ and $\bar{K}'(1) = -2\bar{B}.$

Then the vector

$$|\mathcal{S}\rangle = \langle\langle W|A_1(1)A_2(1)\cdots A_L(1)|V\rangle\rangle,$$

is the stationary state of the process (we have again a telescopic sum):

$$M|\mathcal{S}\rangle = 0$$

More generally, we define the vector

$$|\mathcal{S}(\theta_1, \dots, \theta_L)\rangle = \langle\langle W | A_1(\theta_1) \cdots A_L(\theta_L) | V \rangle\rangle$$

Using the ZF and GZ relations one shows

$$\begin{aligned} |\mathcal{S}(\theta_1, \dots, \theta_L)\rangle &= t(\theta_i | \bar{\theta}) |\mathcal{S}(\theta_1, \dots, \theta_L)\rangle, \\ |\mathcal{S}(\theta_1, \dots, \theta_L)\rangle &= t(1/\theta_i | \bar{\theta}) |\mathcal{S}(\theta_1, \dots, \theta_L)\rangle, \end{aligned}$$

with the **inhomogeneous** transfer matrix

$$t(x | \bar{\theta}) = \text{tr}_0 \left(\tilde{K}_0(x) R_{0L} \left(\frac{x}{\theta_L} \right) \cdots R_{01} \left(\frac{x}{\theta_1} \right) K_0(x) R_{10}(x\theta_1) \cdots R_{L0}(x\theta_L) \right)$$

With the **crossing symmetry** of the R and K matrices:

$$t(x|\bar{\theta}) = \left(\lambda(x|\bar{\theta}) - 1 \right) t(1/xq|\bar{\theta})$$

$\lambda(x|\bar{\theta})$ depends on the considered model.

We get through an interpolation in x

$$t(x|\bar{\theta}) |\mathcal{S}(\theta_1, \dots, \theta_L)\rangle = \lambda(x|\bar{\theta}) |\mathcal{S}(\theta_1, \dots, \theta_L)\rangle$$

Summary

Starting with an R -matrix and two K boundary matrices:

- **We can construct an integrable model**

If R obeys the Yang-Baxter eq. and K, \tilde{K} obey the reflection eq.

- **We can construct the steady state of the model**

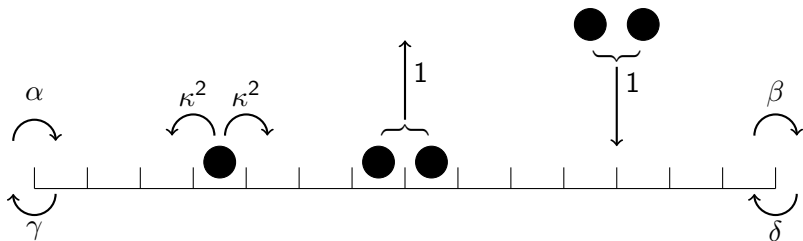
Using a ZF algebra and GZ relations to define the Matrix ansatz

The steady state is an eigenvector of the transfer matrix $t(x|\bar{\theta})$

NB: Contrarily to the Bethe ansatz there is no Bethe parameters (and no Bethe eqs). However, we get only one state...

Example: a reaction-diffusion model

Description of the model:



$$M = B_1 + \sum_{\ell=1}^{L-1} w_{\ell, \ell+1} + \bar{B}_L$$

$$B = \begin{pmatrix} -\alpha & \gamma \\ \alpha & -\gamma \end{pmatrix}, w = \begin{pmatrix} -1 & 0 & 0 & 1 \\ 0 & -\kappa^2 & \kappa^2 & 0 \\ 0 & \kappa^2 & -\kappa^2 & 0 \\ 1 & 0 & 0 & -1 \end{pmatrix}, \bar{B} = \begin{pmatrix} -\delta & \beta \\ \delta & -\beta \end{pmatrix}$$

R-matrix

$$R(x) = \begin{pmatrix} \frac{\kappa(x+1)}{\kappa(x+1)+x-1} & 0 & 0 & \frac{x-1}{\kappa(x+1)+x-1} \\ 0 & \frac{\kappa(x-1)}{\kappa(x-1)+x+1} & \frac{x+1}{\kappa(x-1)+x+1} & 0 \\ 0 & \frac{x+1}{\kappa(x-1)+x+1} & \frac{\kappa(x-1)}{\kappa(x-1)+x+1} & 0 \\ \frac{x-1}{\kappa(x+1)+x-1} & 0 & 0 & \frac{\kappa(x+1)}{\kappa(x+1)+x-1} \end{pmatrix}$$

- Satisfies [Yang-Baxter equation](#), unitarity and regularity relations
- Generates the bulk's local jump operator: $PR'(1) = \frac{1}{2\kappa} w$

K matrices

$$K(x) = \begin{pmatrix} \frac{(x^2+1)((x^2-1)(\gamma-\alpha)+4x\kappa)}{2x((x^2-1)(\alpha+\gamma)+2\kappa(x^2+1))} & \frac{(x^2-1)((x^2+1)(\gamma-\alpha)+2x(\alpha+\gamma))}{2x((x^2-1)(\alpha+\gamma)+2\kappa(x^2+1))} \\ -\frac{(x^2-1)((x^2+1)(\gamma-\alpha)-2x(\alpha+\gamma))}{2x((x^2-1)(\alpha+\gamma)+2\kappa(x^2+1))} & -\frac{(x^2+1)((x^2-1)(\gamma-\alpha)-4x\kappa)}{2x((x^2-1)(\alpha+\gamma)+2\kappa(x^2+1))} \end{pmatrix}$$

$$\bar{K}(x) = \begin{pmatrix} \frac{(x^2+1)((x^2-1)(\delta-\beta)+4x\kappa)}{2x(-(x^2-1)(\delta+\beta)+2\kappa(x^2+1))} & \frac{(x^2-1)((x^2+1)(\delta-\beta)-2x(\delta+\beta))}{2x(-(x^2-1)(\delta+\beta)+2\kappa(x^2+1))} \\ -\frac{(x^2-1)((x^2+1)(\delta-\beta)+2x(\delta+\beta))}{2x(-(x^2-1)(\delta+\beta)+2\kappa(x^2+1))} & -\frac{(x^2+1)((x^2-1)(\delta-\beta)-4x\kappa)}{2x(-(x^2-1)(\delta+\beta)+2\kappa(x^2+1))} \end{pmatrix}$$

- Satisfy the **reflection equation**, the unitarity and regularity relations
- Generate the boundaries local jump operators: $K'(1) = \frac{1}{\kappa} B$ and $\bar{K}'(1) = -\frac{1}{\kappa} \bar{B}$

Construction of the matrix ansatz algebra:

The following expansion of the vector $A(x)$ turns out to be optimal

$$A(x) = \begin{pmatrix} G_1 x + G_2 + \frac{G_3}{x} \\ -G_1 x + G_2 - \frac{G_3}{x} \end{pmatrix}$$

Construction of the matrix ansatz algebra:

The following expansion of the vector $A(x)$ turns out to be optimal

$$A(x) = \begin{pmatrix} G_1 x + G_2 + \frac{G_3}{x} \\ -G_1 x + G_2 - \frac{G_3}{x} \end{pmatrix}$$

Exchange relations in the bulk (ZF algebra):

$$R_{12} \left(\frac{x_1}{x_2} \right) A_1(x_1) A_2(x_2) = A_2(x_2) A_1(x_1) \Leftrightarrow \begin{cases} \phi G_1 G_2 = G_2 G_1 \\ G_1 G_3 = G_3 G_1 \\ \phi G_2 G_3 = G_3 G_2 \end{cases}$$

$$\text{with } \phi = \frac{\kappa - 1}{\kappa + 1}$$

Condition on the left boundary (GZ relation):

$$\langle\langle W|A(x) = \langle\langle W|K(x)A\left(\frac{1}{x}\right) \Leftrightarrow \langle\langle W|(G_1 - c G_2 - a G_3) = 0$$

$$\text{with } a = \frac{2\kappa - \alpha - \gamma}{2\kappa + \alpha + \gamma} \text{ and } c = \frac{\gamma - \alpha}{2\kappa + \alpha + \gamma}$$

Condition on the right boundary (GZ relation):

$$A(x)|V\rangle\rangle = \bar{K}(x)A\left(\frac{1}{x}\right)|V\rangle\rangle \Leftrightarrow (G_3 - b G_1 - d G_2)|V\rangle\rangle = 0$$

$$\text{with } b = \frac{2\kappa - \delta - \beta}{2\kappa + \delta + \beta} \text{ and } d = \frac{\beta - \delta}{2\kappa + \delta + \beta}$$

Matrix ansatz:

$$A(1) = \begin{pmatrix} G_2 + (G_1 + G_3) \\ G_2 - (G_1 + G_3) \end{pmatrix} \quad \text{and} \quad A'(1) = (G_1 - G_3) \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\boxed{\bullet} \longrightarrow D = G_2 - G_1 - G_3$$

$$\boxed{} \longrightarrow E = G_2 + G_1 + G_3$$

Normalization factor:

$$Z_L = \langle\langle W | (D + E)^L | V \rangle\rangle = 2^L \langle\langle W | G_2^L | V \rangle\rangle$$

Computation of the densities:

$$\begin{aligned}\langle n_i \rangle &= \frac{\langle\langle W|(D+E)^{i-1}D(D+E)^{L-i}|V\rangle\rangle}{\langle\langle W|(D+E)^L|V\rangle\rangle} \\ &= \frac{1}{2} \frac{\langle\langle W|G_2^{i-1}(G_2 - G_1 - G_3)G_2^{L-i}|V\rangle\rangle}{\langle\langle W|G_2^L|V\rangle\rangle}\end{aligned}$$

Using solely

$$\begin{cases} \phi G_1 G_2 = G_2 G_1 \\ G_1 G_3 = G_3 G_1 \\ \phi G_2 G_3 = G_3 G_2 \end{cases} \quad \text{and} \quad \begin{cases} \langle\langle W|(G_1 - cG_2 - aG_3) = 0 \\ (G_3 - bG_1 - dG_2)|V\rangle\rangle = 0 \end{cases}$$

$$\text{we get } \langle n_i \rangle = \frac{1}{2} - \frac{c\phi^{i-1} + ad\phi^{L+i-2} + d\phi^{L-i} + bc\phi^{2L-i-1}}{2(1 - ab\phi^{2L-2})}$$

We found a representation where $Z_L = \langle\langle W|G_2^L|V\rangle\rangle$ is non-zero

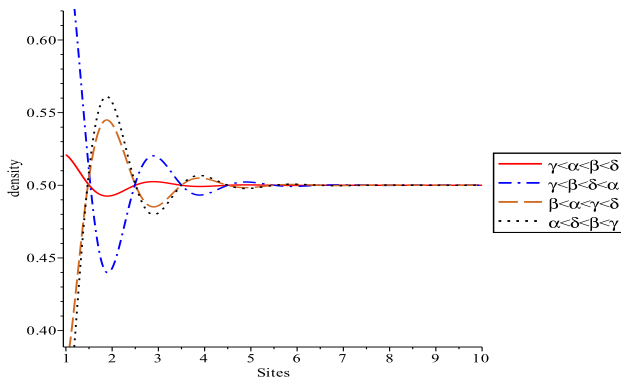


Figure: Density profiles close to the left boundary for various values of the boundary parameters

We can also compute the currents.

Diffusion current from the site i to $i + 1$:

$$\langle J_{i \rightarrow i+1}^{lat} \rangle = \frac{\kappa^2}{\kappa + 1} \frac{d\phi^{L-i-1} + bc\phi^{2L-i-2} - c\phi^{i-1} - ad\phi^{L+i-2}}{1 - ab\phi^{2L-2}}$$

Evaporation current at sites $(i, i + 1)$:

$$\langle J_{i,i+1}^{eva} \rangle = -\frac{\kappa}{\kappa + 1} \frac{c\phi^{i-1} + ad\phi^{L+i-2} + d\phi^{L-i-1} + bc\phi^{2L-i-2}}{1 - ab\phi^{2L-2}}$$

Conclusion

- Comprehension of the **matrix ansatz** in the **integrable systems** framework
- 2 key ingredients: the **ZF algebra** (in the bulk) and the **GZ relations** (on the boundaries)
- In principle it allows us to construct a matrix ansatz for **any** integrable reaction-diffusion process (if we know the R-matrix)
- In practice the matrix ansatz algebra can be very complicated and the computation of observables can be very hard

Perspectives

- Make a better use of the spectral parameter (with the ZF and GZ relations) to extract property of the stationary state
- relations with orthogonal polynomials (see e.g. [arXiv:1506.04874](https://arxiv.org/abs/1506.04874) for shifted Schur polynomials in relation with discrete time TASEP)
- More efficient computation of observables
- Find a prescription for the truncation in the vector $A(x)$ (optimal number of generators)
- Use this framework to compute cumulants (work in progress for the example)
- Solve more complicated models: for instance we solved a 2-species TASEP with boundaries (see [arXiv:1412.5939](https://arxiv.org/abs/1412.5939) with K. Mallick)

Thank you!

Representation for the algebra of the reaction-diffusion model

$$\phi G_1 G_2 = G_2 G_1 ; \quad G_1 G_3 = G_3 G_1 ; \quad \phi G_2 G_3 = G_3 G_2$$

$$G_1 = g_1 \otimes 1, \quad G_2 = g_2 \otimes g_2, \quad G_3 = 1 \otimes g_3,$$

where

$$g_1 = \sum_{n=0}^{+\infty} |n+1\rangle\rangle\langle\langle n| \quad ; \quad g_2 = \sum_{n=0}^{+\infty} \phi^n |n\rangle\rangle\langle\langle n| \quad ; \quad g_3 = \sum_{n=1}^{+\infty} |n-1\rangle\rangle\langle\langle n|$$

We have used $\{|n\rangle\rangle \mid n \geq 0\}$ as an infinite basis of the additional space.

$$\begin{cases} \langle\langle W | (G_1 - cG_2 - aG_3) = 0 \\ (G_3 - bG_1 - dG_2) | V \rangle\rangle = 0 \end{cases}$$

$$|V\rangle\rangle = \sum_{n,m=0}^{+\infty} v_{n,m} |n\rangle\rangle \otimes |m\rangle\rangle \quad ; \quad v_{n,m} = d^{m-n} b^n \frac{\phi^{\frac{(m-n)(m-n-1)}{2}}}{(1-\phi^2) \cdots (1-\phi^{2n})}$$

$$\langle\langle W | = \sum_{n,m=0}^{+\infty} w_{n,m} \langle\langle n | \otimes \langle\langle m | \quad ; \quad w_{n,m} = c^{n-m} a^m \frac{\phi^{\frac{(n-m)(n-m-1)}{2}}}{(1-\phi^2) \cdots (1-\phi^{2m})}$$

$$\begin{aligned}
 Z_L &= \langle\langle W | G_2^L | V \rangle\rangle \\
 &= \sum_{n,m=0}^{+\infty} \frac{(\phi^L cb/d)^n (\phi^L da/c)^m \phi^{(m-n)^2}}{(1-\phi^2)\cdots(1-\phi^{2n}) \times (1-\phi^2)\cdots(1-\phi^{2m})}
 \end{aligned}$$

The series is convergent when

$$|\phi| < 1, \quad \left| \frac{bc\phi^L}{(1-\phi^2)d} \right| < 1 \quad \text{and} \quad \left| \frac{ad\phi^L}{(1-\phi^2)c} \right| < 1$$

Thanks to the symmetry $\kappa \rightarrow -\kappa$, we can choose $|\phi| < 1$.

Then, when L is large enough, the conditions are always fulfilled (when $c, d, \kappa \neq 0$).